

Computational Completeness

1 Definitions and examples

Let $\Sigma = \{f_1, f_2, \dots, f_i, \dots\}$ be a (finite or infinite) set of Boolean functions. Any of the functions $f_i \in \Sigma$ can be a function of arbitrary number of arguments.

Definition 1 *The set Σ is called **computationally complete** (or, simply, complete), if any Boolean function can be expressed as a formula involving just the functions of the set Σ .*

Example 1 *The set $\Sigma_1 = \{\bar{x}_1, x_1 \vee x_2, x_1 \wedge x_2\}$ is complete, because any Boolean function can be represented in the SOP or in the POS form, and these representations involve just the functions of Σ_1 .*

Example 2 *The set $\Sigma_2 = \{\bar{x}_1, x_1 \wedge x_2\}$ is complete, because $x_1 \vee x_2 = \overline{\bar{x}_1 \wedge \bar{x}_2}$. Therefore, the completeness of Σ_2 follows from the completeness of Σ_1 .*

Example 3 *The set $\Sigma_3 = \{x_1|x_2\}$, where $x_1|x_2 = \overline{x_1 \wedge x_2}$, is complete. Indeed,*

$$x_1|x_1 = \bar{x}_1, \quad (x_1|x_2)|(x_1|x_2) = x_1 \wedge x_2.$$

Thus, the question concerning the completeness of Σ_3 is reduced to one of Σ_2 .

Example 4 *The set $\Sigma_4 = \{1, x_1 \wedge x_2, x_1 \oplus x_2\}$, where $x_1 \oplus x_2$ is the XOR function and 1 is the constant function, is complete. Indeed, $x_1 \oplus 1 = \bar{x}$. Hence, the completeness of Σ_4 follows from the completeness of Σ_2 .*

Example 5 *The set $\Sigma_5 = \{1, x_1 \wedge x_2\}$ is not complete, because any function that can be expressed by a formula involving just the functions of Σ_5 is either the constant function 1 or the function of the form $x_1 \wedge x_2 \wedge \dots \wedge x_n$ for $n = 2, 3, \dots$*

Given a set Σ of Boolean functions, how to recognize if Σ is complete? In order to present a complete answer to this question we introduce 5 following classes of Boolean functions: T_0 , T_1 , L , S , and M .

2 The class T_0

Definition 2 *The class T_0 consists of all Boolean functions f (of any number of arguments) defined as follows:*

$$T_0 = \{f(x_1, \dots, x_n) \mid f(0, 0, \dots, 0) = 0\}.$$

Example 6 The following functions belong to the class T_0 : $0, x_1 \wedge x_2, x_1 \vee x_2, x_1 \oplus x_2$.

Example 7 The functions 1 and \bar{x}_1 are not in T_0 .

The number of function in T_0 which depend on n variables is $2^{2^n-1} = \frac{1}{2} \cdot 2^{2^n}$.

3 The class T_1

Definition 3 The class T_1 consists of all Boolean functions f (of any number of arguments) defined as follows:

$$T_1 = \{f(x_1, \dots, x_n) \mid f(1, 1, \dots, 1) = 1\}.$$

Example 8 The following functions belong to the class T_1 : $1, x_1 \wedge x_2, x_1 \vee x_2$.

Example 9 The functions $x_1 \oplus x_2$ and \bar{x}_1 are not in T_1 .

The number of function in T_1 which depend on n variables also equals $2^{2^n-1} = \frac{1}{2} \cdot 2^{2^n}$.

4 The class L of linear functions

Definition 4 The class L consists of functions (of any number of arguments) that can be represented in the form

$$L = \{f(x_1, \dots, x_n) \mid f = (a_1 \wedge x_1) \oplus (a_2 \wedge x_2) \oplus \dots \oplus (a_n \wedge x_n) \oplus b\},$$

where $a_1, \dots, a_n, b \in \{0, 1\}$ are some fixed constants.

Example 10 Since $\bar{x}_1 = x_1 \oplus 1$, then $\bar{x}_1 \in L$.

Example 11 $x_1 \vee x_2 \notin L$. Indeed, assume the contrary, i.e. $x_1 \vee x_2 \in L$. Then $x_1 \vee x_2 = (a_1 \wedge x_1) \oplus (a_2 \wedge x_2) \oplus b$ for some constants $a_1, a_2, b \in \{0, 1\}$. Since $x_1 \vee x_2$ significantly depends on two variables (i.e. cannot be represented as a function of one or less variables), then $a_1 = a_2 = 1$, because otherwise we would get a function depending on just one variable. Hence, our representation should be of the form $x_1 \vee x_2 = x_1 \oplus x_2 \oplus b$ for some $b \in \{0, 1\}$.

Now if we assume $b = 0$, then $x_1 \vee x_2 = x_1 \oplus x_2$, which is a contradiction. Otherwise, if $b = 1$, then $x_1 \vee x_2 = x_1 \oplus x_2 \oplus 1 = \overline{x_1 \oplus x_2}$, which is a contradiction too. The only way to avoid a contradiction is to accept $x_1 \vee x_2 \notin L$.

Similarly $x_1 \wedge x_2 \notin L$.

The number of functions in L which depend on n variables is 2^{n+1} , because any such a function can be encoded by the binary vector $(a_1, a_2, \dots, a_n, b)$ consisting of $n + 1$ entries.

5 The class S of self-dual functions

Definition 5 A Boolean function is called **self-dual** if

$$f(x_1, \dots, x_n) = \bar{f}(\bar{x}_1, \dots, \bar{x}_n)$$

for any $x_1, \dots, x_n \in \{0, 1\}$.

The class S consists of all self-dual Boolean functions (of any number of variables).

Example 12 Obviously, $\bar{x}_1 \in S$. A more complicated example is the majority function

$$f(x_1, x_2, x_3) = x_1x_2 \vee x_1x_3 \vee x_2x_3.$$

Indeed, using the DeMorgan's theorem

$$\begin{aligned} \bar{f}(\bar{x}_1, \bar{x}_2, \bar{x}_3) &= \overline{\bar{x}_1\bar{x}_2 \vee \bar{x}_1\bar{x}_3 \vee \bar{x}_2\bar{x}_3} \\ &= \overline{\bar{x}_1\bar{x}_2} \wedge \overline{\bar{x}_1\bar{x}_3} \wedge \overline{\bar{x}_2\bar{x}_3} \\ &= (x_1 \vee x_2)(x_1 \vee x_3)(x_2 \vee x_3) \\ &= x_1x_2 \vee x_1x_3 \vee x_2x_3 \\ &= f(x_1, x_2, x_3). \end{aligned}$$

Example 13 The functions $f_1(x_1, x_2) = x_1 \wedge x_2$ and $f_2(x_1, x_2) = x_1 \vee x_2$ do not belong to S . Indeed, $f_1(0, 1) = f_1(1, 0)$ and $f_2(0, 1) \neq f_2(1, 0)$.

What is the number of the self-dual functions depending on n variables? To compute this number, represent the function $f(x_1, \dots, x_n) \in S$ by the logical table with 2^n rows, which we split into two equal parts, consisting of 2^{n-1} rows each:

$x_1 \ x_2 \ \dots \ x_n$	$f(x_1, \dots, x_n)$
0 0 \dots 0 0	α
0 0 \dots 0 1	
\dots	
0 1 \dots 1 1	
1 0 \dots 0 0	
1 0 \dots 0 1	
\dots	
1 1 \dots 1 1	$\bar{\alpha}$

Note that the i^{th} row of the left part of the table is the negation of the $(2^n - i)^{th}$ row. If $f(x_1, \dots, x_n) \in S$ then the value of f in these rows are different. Therefore, f is completely determined by the values it takes on just in the upper (or just lower) part of the table. In other words, the number of the self-dual functions in question equals the number of binary strings of length 2^{n-1} , i.e. $2^{2^{n-1}} = \sqrt{2^{2^n}}$.

6 The class M of monotone functions

Definition 6 Let (x_1, \dots, x_n) and (y_1, \dots, y_n) be two binary vectors of the same dimension. We write $(x_1, \dots, x_n) \leq (y_1, \dots, y_n)$ if $x_i \leq y_i$ for $i = 1, 2, \dots, n$.

If $(x_1, \dots, x_n) \not\leq (y_1, \dots, y_n)$ and $(y_1, \dots, y_n) \not\leq (x_1, \dots, x_n)$ then we say that these vectors are **incompatible**.

Example 14 It holds: $(0, 1, 0) \leq (1, 1, 0)$, and $(0, 0, \dots, 0) \leq (1, 1, \dots, 1)$.

Example 15 The vectors $(0, 1, 0)$ and $(1, 0, 0)$ are incompatible. In general, a vector and its binary coordinatewise negation are incompatible, cf. e.g. $(0, 1, 0)$ and $(1, 0, 1)$.

Definition 7 We call a function $f(x_1, \dots, x_n)$ **monotone** if $f(x_1, \dots, x_n) \leq f(y_1, \dots, y_n)$ whenever $(x_1, \dots, x_n) \leq (y_1, \dots, y_n)$.

Example 16 The functions $x_1 \wedge x_2$ and $x_2 \vee x_2$ are monotone, however the functions \bar{x}_1 and $x_1 \oplus x_2$ are not.

Denote by M_n the number of monotone Boolean functions of n variables. The problem of computing M_n was posed by Dedekind in 1897 (!) and is still unsolved up to now. It is known that

n	M_n
0	2
1	3
2	6
3	20
4	168
5	7581
6	7828354

Many mathematicians contributed to this problem. The most recent to our knowledge result (cf. [1, 4]) is the asymptotic formula for M_n as $n \rightarrow \infty$:

$$M_n \sim \begin{cases} 2^{\binom{n}{n/2}} \exp \left\{ \binom{n}{n/2-1} \left(2^{-n/2} + n^2 \cdot 2^{-n-5} - n \cdot 2^{-n-4} \right) \right\}, & \text{if } n \text{ is even} \\ 2 \cdot 2^{\binom{n}{(n-1)/2}} \exp \left\{ \binom{n}{(n+1)/2} \left(2^{-(n+1)/2} + n^2 \cdot 2^{-n-4} \right) + \right. \\ \left. + \binom{n}{(n-3)/2} \left(2^{-(n+3)/2} - n^2 \cdot 2^{-n-6} - n \cdot 2^{-n-3} \right) \right\}, & \text{if } n \text{ is odd.} \end{cases}$$

7 The criterion for completeness

Let $\Sigma = \{f_1, f_2, \dots, f_i, \dots\}$ be a set of Boolean functions.

Theorem 1 (E. Post [2, 3])

The set Σ is complete if and only if for any of the classes T_0, T_1, L, S, M there exists a function of Σ which is not in this class.

In order to apply this theorem to the set Σ we construct the following table:

	T_0	T_1	L	S	M
f_1					
f_2					
\dots					
f_i					
\dots					

with entries of the set $\{+, -\}$. The entry “+” in the i^{th} row means that the function f_i belongs to the corresponding class. Then, by the theorem of Post, the set Σ is complete if and only if each column of this table contains at least one “-”.

Example 17 Consider the system $\Sigma_1 = \{\bar{x}_1, x_1 \vee x_2, x_1 \wedge x_2\}$. One has:

	T_0	T_1	L	S	M
\bar{x}_1	-	-	+	+	-
$x_1 \vee x_2$	+	+	-	-	+
$x_1 \wedge x_2$	+	+	-	-	+

Thus, by the theorem of Post the set Σ is complete.

Moreover, one of the last two functions (but not both) can be deleted from Σ without the loss of the completeness of the remaining set. In such a way the complete system Σ_2 of Example 2 can be obtained.

Example 18 Consider the following set Σ :

$$f_1 = x_1x_2, f_2 = 0, f_3 = 1, f_4 = x_1 \oplus x_2 \oplus x_3.$$

One has

	T_0	T_1	L	S	M
f_1	+	+	-	-	+
f_2	+	-	+	-	+
f_3	-	+	+	-	+
f_4	+	+	+	+	-

Thus, Σ is complete. However, deleting of any function from σ makes the remaining set incomplete because

$$\begin{aligned} \{f_2, f_3, f_4\} &\subset L & \{f_1, f_3, f_4\} &\subset T_1 \\ \{f_1, f_2, f_4\} &\subset T_0 & \{f_1, f_2, f_3\} &\subset M \end{aligned}$$

Corollary 1 Any complete set Σ of functions contains a complete subset consisting of at most 5 functions of Σ .

In fact a more strong result holds: any complete set can be reduced to a complete subset consisting of at most 4 functions. As Example 18 shows, this proposition cannot be further improved in general.

References

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