

# Time complexity

- Here we will consider *elements of computational complexity theory* – an investigation of the time (or other resources) required for solving computational problems.
- We introduce a way of measuring the time used to solve a problem. Then we will classify problems according to the amount of time required.
- We will see that certain decidable problems require enormous amounts of time and how to determine when you are faced with such a problem.
- Let consider an example of a TM  $M1$  which decides the language  $A = \{0^k 1^k : k \geq 0\}$ .

$M1$  = “on input  $w$ :

1. Scan across the tape and *reject* if a 0 is found to the right of a 1.
2. Repeat the following if both 0s and 1s remain on the tape.
3.     Scan across the tape, crossing off a single 0 and a single 1.
4. If 0s still remain after all the 1s have been crossed off, or if 1s remain after all the 0s have been crossed off, *reject*. Otherwise, if neither 0s nor 1s remain on the tape, *accept*.”

- How much time does a single type TM need to decide  $A$ ?
- We count the number of steps that algorithm uses on a particular input as a function of the length of the string representing the input.
- We consider *worst case analysis*, i.e., the longest running time of all inputs of a particular length.

# Asymptotic notation : big- $O$ and small- $o$

- **Def. 1:** Let  $M$  be a TM that halts on all inputs. The **running time** or **time complexity** of  $M$  is the function  $f: N \rightarrow N$ , where  $f(n)$  is the maximum number of steps that  $M$  uses on any input of length  $n$ . We say  $M$  runs in time  $f(n)$  and  $M$  is an  $f(n)$  time Turing machine.
- **Def. 2:** Let  $f$  and  $g$  be two functions  $f, g: N \rightarrow R^+$ . Say that  $f(n) = O(g(n))$  if positive integers  $c$  and  $n'$  exist so that for every  $n \geq n'$ ,  $f(n) \leq c g(n)$ . We say that  $g(n)$  is an **upper bound** for  $f(n)$  (or **asymptotic upper bound**).
- Intuitively, this means that  $f$  is less than or equal to  $g$  for sufficient large  $n$  if we disregard differences up to a constant factor.  $O$  represents that constant; constant is hidden under  $O$ .
  - If  $f(n) = 5n^3 + 2n^2 + 22n + 6$ , then  $f(n) = O(n^3)$  or  $f(n) = O(n^4)$ , but  $f(n) \neq O(n^2)$ .
  - If  $f(n) = 3n \log_2 n + 5n \log_2 \log_2 n + 2$ , then  $f(n) = O(n \log n)$ .
  - If  $f(n) = O(n^2) + O(n)$ , then  $f(n) = O(n^2)$ .
- Other examples of run-time:  $2^{O(n)}$ ,  $O(1)$ ,  $n^{O(1)}$  ( $= 2^{O(\log n)}$ ). Bounds of the form  $n^c$  for  $c > 0$  are called **polynomial bounds**. Bounds of the form  $2^{(n^\delta)}$  ( $\delta > 0$ ) are called **exponential bounds**.
- **Def. 3:** Let  $f$  and  $g$  be two functions  $f, g: N \rightarrow R^+$ . Say that  $f(n) = o(g(n))$  if for any real  $c > 0$ , a number  $n'$  exists so that for every  $n \geq n'$ ,  $f(n) < c g(n)$ .
- Examples:
 

$\sqrt{n} = o(n),$	$n = o(n \log \log n),$	$\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0.$
$n \log \log n = o(n \log n),$	$n \log n = o(n^2),$	
$n^2 = o(n^3),$	$\text{but } f(n) \neq o(f(n)).$	

# Analyzing Algorithms

Let's analyze the algorithm we gave for the language  $A = \{0^k 1^k : k \geq 0\}$ .

*M1* = “on input  $w$ :

1. Scan across the tape and *reject* if a 0 is found to the right of a 1.
2. Repeat the following if both 0s and 1s remain on the tape.
  3. Scan across the tape, crossing off a single 0 and a single 1.
4. If 0s still remain after all the 1s have been crossed off, or if 1s remain after all the 0s have been crossed off, *reject*. Otherwise, if neither 0s nor 1s remain on the tape, *accept*.”

- **Stage 1:** verifies that input is of form  $0^*1^*$  in  $2n$  steps. Hence  $O(n)$  steps.
- **Stages 2,3:** each scan uses  $O(n)$  steps, at most  $n/2$  scans. Hence  $O(n^2)$  steps.
- **Stage 4:** at most  $O(n)$  steps.
- Hence, the total time of *M1* on input of length  $n$  is  $O(n) + O(n^2) + O(n) = O(n^2)$ .

• **Def. 4:** Let  $t : N \rightarrow N$  be a function. Define the time complexity class,  $TIME(t(n))$ , to be

$$TIME(t(n)) = \{L : L \text{ is a language decided by an } O(t(n)) \text{ time Turing machine}\}.$$

- We have  $A \in TIME(n^2)$ . Is there a machine that decides  $A$  asymptotically more quickly?

$$A = \{0^k 1^k : k \geq 0\} \in TIME(n \log n)$$

$M2$  = “on input  $w$ :

1. Scan across the tape and *reject* if a  $0$  is found to the right of a  $1$ .
2. Repeat the following if some  $0$ s and some  $1$ s remain on the tape.
  3. Scan across the tape, checking whether the total number of  $0$ s and  $1$ s remaining is even or odd. If odd, *reject*.
  4. Scan again across the tape, crossing off every other  $0$  starting with the first  $0$ , and then crossing off every other  $1$  starting with the first  $1$ .
5. If no  $0$ s and no  $1$ s remain on the tape, *accept*. Otherwise, *reject*.”

- ***Why does  $M2$  decide  $A$ ?***

- on every scan performed in stage 4, the total number of  $0$ s (of  $1$ s) remaining is cut in half and any remainder is discarded.
- in stage 3 we check whether the parities of # of  $0$ s and # of  $1$ s are the same.

- **Running Time:**

- *All Stages* take  $O(n)$  steps.
- *Stages 1 and 5* are executed once.
- *Stages 2,3,4* are executed at most  $(1+\log n)$  time.
- Hence, the total time of  $M2$  on input of length  $n$  is
 
$$O(n) + (1 + \log n)(O(n) + O(n) + O(n)) + O(n) = O(n \log n).$$
- So,  $A \in TIME(n \log n)$ . This result cannot be further improved on a single tape TM.

# Linear time two-tape Turing machine for $A$ .

$M3$  = “on input  $w$ :

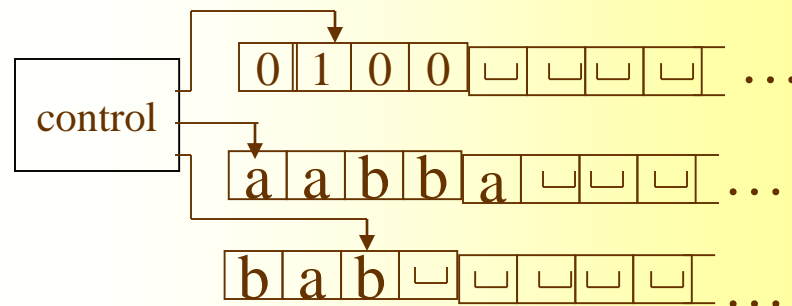
1. Scan across the tape and *reject* if a  $0$  is found to the right of a  $1$ .
2. Scan across the  $0$ s on tape 1 until the first  $1$ . At the same time, copy the  $0$ s onto tape 2.
3. Scan across the  $1$ s on tape 1 until the end of the input. For each  $1$  read on tape 1, cross off a  $0$  on tape 2. If all  $0$ s are crossed off before all the  $1$ s are read, *reject*.
4. If all the  $0$ s have now been crossed off, *accept*. If any  $0$ s remain, *reject*.”

- Clearly, this is a decider for  $A$ . Running time is clearly  $O(n)$ .
- **Summary:**
  - We presented a single tape TM  $M2$  that decides  $A$  in  $O(n \log n)$  time.
  - We mentioned (w/o proof) that no single tape TM can do it more quickly.
  - Then we presented a two-tape TM  $M3$  that decides  $A$  in linear time.
  - Hence, the complexity of  $A$  depends on the model of computation selected.
- This shows an important difference between *complexity theory* and *computability theory*.
- In *computability theory*, The Church-Turing thesis implies that all reasonable models of computation are equivalent, i.e., they decide the same class of languages. In *complexity theory*, the choice of model affects the time complexity of languages.

# Complexity relations among models: Multi-tape TM

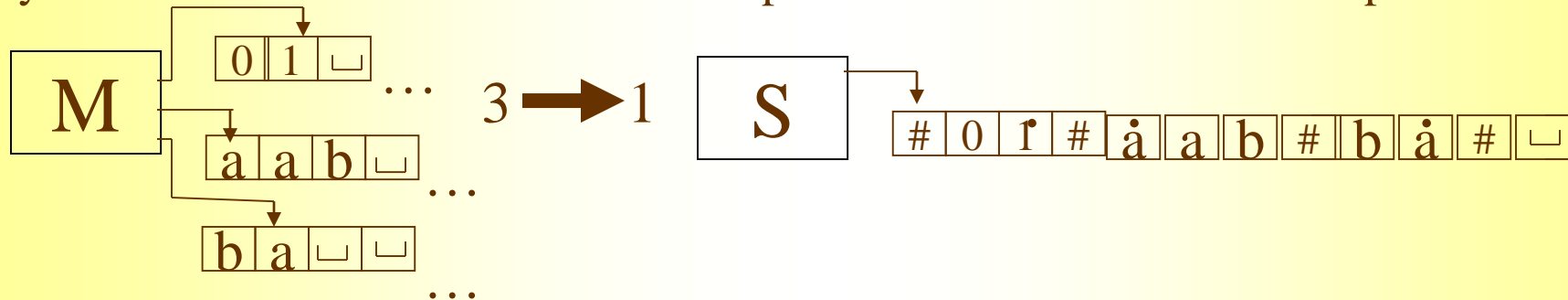
$$\delta: Q \times \Gamma^k \rightarrow Q \times \Gamma^k \times \{L, R\}^k,$$

$$\delta(q, a_1, \dots, a_k) = (r, b_1, \dots, b_k, L, R, \dots, L)$$



**Theorem 1:** Let  $t(n)$  be a function, where  $t(n) \geq n$ . Then every  $t(n)$  time multi-tape TM has an equivalent  $O(t^2(n))$  time single-tape TM.

- We have seen before how to convert a multi-tape TM  $M$  to an equivalent single tape TM  $S$ , that simulates it.
- Let  $M$  be a  $k$ -tape TM that runs in  $t(n)$  time. We will show that simulating each step of the multi-tape TM uses at most  $O(t(n))$  steps of the single-tape TM. Hence the total time used is  $O(t^2(n))$ .
- $S$  simulates the effect of  $k$  tapes by storing their information on its single tape.
- It uses new symbol  $\#$  as a delimiter to separate the contents of the different tapes.
- $S$  must also keep track of the locations of the heads. It does so by writing a tape symbol with a dot above it to mark the place where the head on that tape would be.





# Multi-tape TM vs. Single-tape TM

$S =$  “On input  $w = w_1 w_2 \dots w_n$  :

1. First  $S$  puts its tape into the format that represents all  $k$  tapes of  $M$ . The formatted tape contains  $\# w_1 w_2 \dots w_n \# \sqcup \# \sqcup \# \dots \#$
2. To simulate a single move,  $S$  scans its tape from the first  $\#$ , which marks the left-hand end, to the  $(k+1)$ st  $\#$ , which marks the right-hand end, in order to determine the symbols under the virtual heads. Then  $S$  makes a second pass to update the tapes according to the way that  $M$ 's transition function dictates.
3. If at any point  $S$  moves one of the virtual heads to the right onto a  $\#$ , this action signifies that  $M$  has moved the corresponding head onto the previously unread blank portion of that tape. So  $S$  writes a blank symbol on this tape cell and shifts the tape contents, from this cell until the rightmost  $\#$ , one unit to the right. Then it continues the simulation as before.

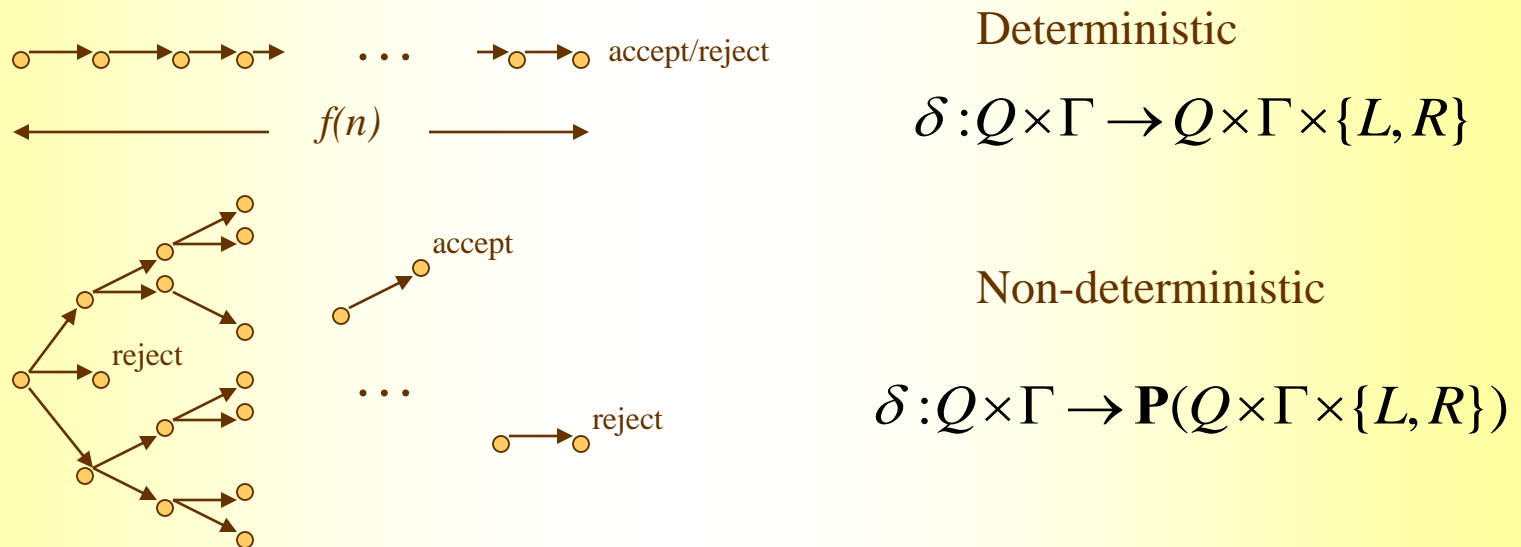
## **Running Time:**

- **Stage 1** takes  $O(n)$  steps and is executed once.
- **Stages 2,3:**  $S$  simulates each of the  $t(n)$  steps of  $M$ , using  $O(t(n))$  steps.
  - The length of the active portion of  $S$ 's tape determines how long  $S$  takes to scan it.
  - A scan of the active portion of  $S$ 's tape uses  $O(t(n))$  steps. (Why???)
- Hence, the total time of  $S$  on input of length  $n$  is
$$O(n) + t(n) \times O(t(n)) = O(t^2(n)).$$

# Complexity relations among models: Non-deterministic TM

- A non-deterministic TM is a decider if all its computation branches halt on all inputs.

- **Def 5:** Let  $N$  be a non-deterministic TM that is a decider. The **running time** of  $N$  is the function  $f: N \rightarrow N$ , where  $f(n)$  is the maximum number of steps that  $N$  uses on any branch of its computation on any input of length  $n$ .



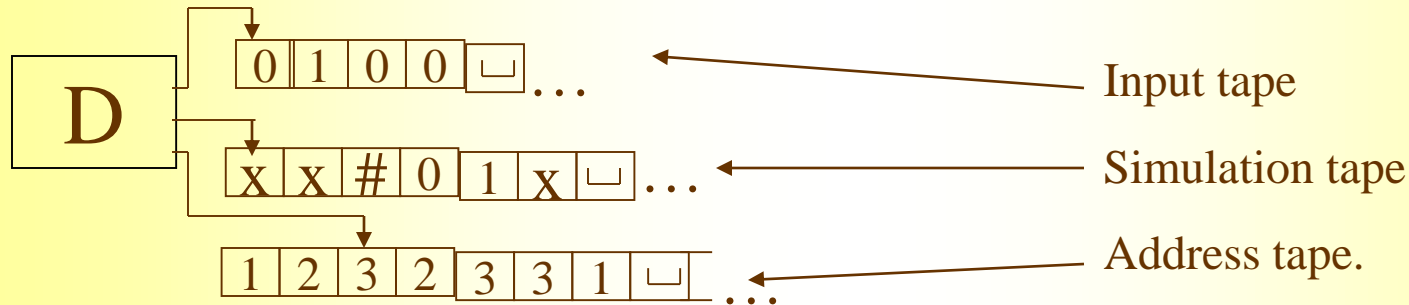
**Theorem 2:** Let  $t(n)$  be a function, where  $t(n) \geq n$ . Then every  $t(n)$  time non-deterministic TM has an equivalent  $2^{O(t(n))}$  time deterministic TM.

- We have seen before that any non-deterministic TM  $N$  has an equivalent deterministic TM  $D$ , that simulates it.



# Non-deterministic TMs vs. ordinary TMs

- The simulating deterministic TM  $D$  has three tapes.
  - Tape 1 always contains the input string and is never altered.
  - Tape 2 maintains a copy of  $N$ 's tape on some branch of its non-deterministic computation.
  - Tape 3 keeps track of  $D$ 's location in  $N$ 's non-deterministic computation tree.



- Every node in the tree can have at most  $b$  children, where  $b$  is the size of the largest set of possible choices given by  $N$ 's transition function.
- Tape 3 contains a string over  $\Sigma_b = \{1, 2, \dots, b\}^*$ . Each symbol in the string tells us which choice to make next when simulating a step in one branch in  $N$ 's non-deterministic computation. This gives the address of a node in the tree.
- On an input of length  $n$ , every branch of  $N$ 's non-deterministic computation tree has a length of at most  $t(n)$ . Hence the total number of leaves in the tree is at most  $b^{t(n)}$ .
- The total number of nodes in the tree is less than twice the maximum number of leaves, i.e. is bounded by  $O(t(n))$ . Hence the running time of  $D$  is  $O(t(n)b^{t(n)}) = 2^{O(t(n))}$ .
- $D$  has three tapes. Converting it to a single tape TM  $S$  at most squares the running time.
- So, the running time of  $S$  is  $(2^{O(t(n))})^2 = 2^{O(2t(n))} = 2^{O(t(n))}$ .